Amendments to the Specification:

Please replace the paragraph on page 10, lines 18-31, with the following amended paragraph:

The web splicer depicted in Figs. 8-10 includes a servo motor 223, a gear 228 integrally connected to a gearshaft 229, the gearshaft 229 being driven via a gearbox 230 by the servo motor 223, the carriage 26 having a rack ~~231~~ 237 having rack teeth 232 which engage teeth 233 of the gear 228, the servo motor 223 being activated (upon receiving an engage signal) to drive the gearshaft 229 and gear 228 so as to move the carriage 26 from the first carriage position (shown in Fig. 8) to the second carriage position (shown in Fig. 9), thereby moving the paster roll 21 from a first location (shown in Fig. 8) where it is not abutting the second roll 14 to a second location (shown in Fig. 9) where it abuts the second roll 14. Upon receiving a disengage signal (after the splice has been completed), the servo motor 223 is again activated to drive the gearshaft 229 and gear 228 in the opposite direction so as to move the carriage 26 from the second carriage position (shown in Fig. 9) back to the first carriage position (shown in Fig. 8), thereby moving the paster roll 21 from the second location (shown in Fig. 9) where it is abutting the second roll 14 back to the first location (shown in Fig. 8) where it is not abutting the second roll 14.